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Calculate the mobility of these mechanisms. Figure P.3.4 Spatial mechanisms comprised of R, P, C and S joints 10. Compile a table of 2 DOF planar mechanisms having 4 and 5 links (considering cam or gear joints as 2 J). Illustrate one four-bar mechanism solution and one five-bar mechanism solution.

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Sandor & Erdman, Advanced Mechanism Design: Analysis and ...

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