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[Dynamic Systems](#) Elsevier

In this book, Mathematical Modelling of a reference SEDM has been done & Transfer Function has been derived with simulated result. Later Parameter Identification has been carried out to find the suitable design criteria for testing different controllers (P, PI, PD, PID controllers) with the machine. As it turned out to be a stable system (as per Routh-Hurwitz Stability Criterion), different controllers has been used to evaluate the Step response of Open loop & Closed loop system with simulated result. Controller tuning has been done to find the best result for controlling speed of SEDM. Settling time, % Overshoot, Steady-State error & Rise time has been calculated for all the controllers. Later active RC realization of the best fitted controller has been done using Ideal PID Control Algorithm.

Sliding Mode Control Using Novel Sliding Surfaces CRC Press

This book comprises select proceedings of the International Conference on Advances in Electrical and Computer Technologies 2020 (ICAECT 2020). The papers presented in this book are peer-reviewed and cover latest research in electrical, electronics, communication and computer engineering. Topics covered include smart grids, soft computing techniques in power systems, smart energy management systems, power electronics, feedback control systems, biomedical engineering, geo informative systems, grid computing, data mining, image and signal processing, video processing, computer vision, pattern recognition, cloud computing, pervasive computing, intelligent systems, artificial intelligence, neural network and fuzzy logic, broad band communication, mobile and optical communication, network security, VLSI, embedded systems, optical networks and wireless communication. The volume can be useful for students and researchers working in the different overlapping areas of electrical, electronics and communication engineering.

Modeling and Controlling Springer Science & Business Media

The theory of Laplace transformation is an important part of the mathematical background required for engineers, physicists and mathematicians. Laplace transformation methods provide easy and effective techniques for solving many problems arising in various fields of science and engineering, especially for solving differential equations. What the Laplace transformation does in the field of differential equations, the z-transformation achieves for difference equations. The two theories are parallel and have many analogies. Laplace and z transformations are also referred to as operational calculus, but this notion is also used in a more restricted sense to denote the operational calculus of Mikusinski. This book does not use the operational calculus of Mikusinski, whose approach is based on abstract algebra and is not readily accessible to engineers and scientists. The symbolic computation capability of Mathematica can now be used in favor

of the Laplace and z-transformations. The first version of the Mathematica Package LaplaceAndzTransforms developed by the author appeared ten years ago. The Package computes not only Laplace and z-transforms but also includes many routines from various domains of applications. Upon loading the Package, about one hundred and fifty new commands are added to the built-in commands of Mathematica. The code is placed in front of the already built-in code of Laplace and z-transformations of Mathematica so that built-in functions not covered by the Package remain available. The Package substantially enhances the Laplace and z-transformation facilities of Mathematica. The book is mainly designed for readers working in the field of applications.

Linear Systems Control Springer Nature

This book describes a new control design technique called Coefficient Diagram Method (CDM), whereby practical control engineers without deep control theories and mathematics background can design a good controller for their specific plants. In addition, control experts can solve some complicated design problems. Since the CDM was first introduced in 1998, it reveals from the literature that CDM has provided successful controller designs for a variety of practical control problems. In the last two decades, a great deal of research has been done on CDM, while a growing number of researchers want to learn and utilize the method. However, there has been no textbook to learn it systematically so far. This book is motivated by such a need. It is also suitable as a textbook or reference book for master programs in control engineering.

Changeable and Reconfigurable Manufacturing Systems Birkh ä user

After a survey paper by Utkin in the late 1970s, sliding mode control methodologies emerged as an effective tool to tackle uncertainty and disturbances which are inevitable in most of the practical systems. Sliding mode control is a particular class of variable structure control which was introduced by Emel'yanov and his colleagues. The design paradigms of sliding mode control has now become a mature design technique for the design of robust controller of uncertain system. In sliding mode technique, the state trajectory of the system is constrained on a chosen manifold (or within some neighborhood thereof) by an appropriate control action. This manifold is also called a switching surface or a sliding surface. During sliding mode, system dynamics is governed by the chosen manifold which results in a well celebrated invariance property towards certain classes of disturbance and model mismatches. The purpose of this monograph is to give a different dimension to sliding surface design to achieve high performance of the system. Design of the switching surface is vital because the closed loop dynamics is governed by the parameters of the sliding surface. Therefore sliding surface should be designed to meet the closed loop specifications. Many systems demand high performance with robustness. To address this issue of achieving high performance with robustness, we propose nonlinear surfaces for different classes of systems. The nonlinear surface is designed such that it

changes the system's closed-loop damping ratio from its initial low value to a final high value.

Select Proceedings of ICAECT 2020 CRC Press
Servo Motors and Industrial Control Theory is the only text focused on the fundamentals of servo motors and control theory. Graphical methods for classical control theory have been augmented with worked examples using MatLab and Mathcad to reflect the reality of the way engineers solve control problems in the field today. State variable feedback control theory is introduced clearly and simply, with practical examples that help students approach what can be seen as complicated problems with confidence. This updated second edition includes expanded discussion of Nyquist and Root Locus stability criteria and the role of sensors, as well as new Mathcad examples. A range of parameters are introduced for each servo control system discussed, making this book a comprehensive learning tool for students and an accessible information resource for control system designers who want to keep their knowledge up-to-date. The author encourages readers with any inquiries regarding the book to contact him at riazollah@yahoo.com.

Automatic Control with Experiments John Wiley & Sons

The development of computer software for nonlinear control systems has provided many benefits for teaching, research, and the development of control systems design. MATLAB is considered the dominant software platforms for linear and nonlinear control systems analysis. This book provides an easy way to learn nonlinear control systems such as feedback linearization technique and Sliding mode control (Structure variable control) which are one of the most used techniques in nonlinear control dynamical systems; therefore teachers-students and researchers are all in need to handle such techniques; and since they are too difficult for them to handle such nonlinear controllers especially for a more complicated systems such as induction motor, satellite, and vehicles dynamical models. Thus, this document it is an excellent resource for learning the principle of feedback linearization and sliding mode techniques in an easy and simple way: Provides a briefs description of the feedback linearization and sliding mode control strategies Includes a simple method on how to determine the right and appropriate controller (P-PI-PID) for feedback linearization control strategy. A Symbolic MATLAB Based function for finding the feedback linearization and sliding mode controllers are developed and tested using several examples. A simple method for finding the approximate sliding mode controller parameters is introduced Where the program used to construct the nonlinear controller uses symbolic computations; such that the user should provide the program with the necessary functions $f(x)$, $g(x)$ and $h(x)$ using the symbolic library.

Lulu.com

This book is a collection of papers presented at the International Conference on Renewable Power (ICRP

2020), held during 13 – 14 July 2020 in Rajouri, Jammu, India. The book covers different topics of renewable energy sources in modern power systems. The book focusses on smart grid technologies and applications, renewable power systems including solar PV, solar thermal, wind, power generation, transmission and distribution, transportation electrification and automotive technologies, power electronics and applications in renewable power system, energy management and control system, energy storage in modern power system, active distribution network, artificial intelligence in renewable power systems, and cyber-physical systems and Internet of things in smart grid and renewable power.

The Use of an Artificial Neural Network for the Angular Position Control of a Simulated Nonlinear DC Motor CRC Press

This textbook presents theory and practice in the context of automatic control education. It presents the relevant theory in the first eight chapters, applying them later on to the control of several real plants. Each plant is studied following a uniform procedure: a) the plant's function is described, b) a mathematical model is obtained, c) plant construction is explained in such a way that the reader can build his or her own plant to conduct experiments, d) experiments are conducted to determine the plant's parameters, e) a controller is designed using the theory discussed in the first eight chapters, f) practical controller implementation is performed in such a way that the reader can build the controller in practice, and g) the experimental results are presented. Moreover, the book provides a wealth of exercises and appendices reviewing the foundations of several concepts and techniques in automatic control. The control system construction proposed is based on inexpensive, easy-to-use hardware. An explicit procedure for obtaining formulas for the oscillation condition and the oscillation frequency of electronic oscillator circuits is demonstrated as well.

Deterministic and Stochastic Methods John Wiley & Sons

This book presents the proceedings of the IUPESM World Biomedical Engineering and Medical Physics, a tri-annual high-level policy meeting dedicated exclusively to furthering the role of biomedical engineering and medical physics in medicine. The book offers papers about emerging issues related to the development and sustainability of the role and impact of medical physicists and biomedical engineers in medicine and healthcare. It provides a unique and important forum to secure a coordinated, multileveled global response to the need, demand and importance of creating and supporting strong academic and clinical teams of biomedical engineers and medical physicists for the benefit of human health.

Practical QFT Solutions Springer Nature

“Changeable and Reconfigurable Manufacturing Systems” discusses key strategies for success in the changing manufacturing environment. Changes can often be anticipated but some go beyond the design range, requiring innovative change enablers and adaptation mechanisms. The book presents the new concept of Changeability as an umbrella framework that encompasses paradigms such as agility, adaptability, flexibility and reconfigurability. It provides the definitions and classification of key terms in this new field, and emphasizes the required physical/hard and logical/soft

change enablers. The book presents cutting edge technologies and the latest research, as well as future directions to help manufacturers stay competitive. It contains original contributions and results from senior international experts, together with industrial applications. The book serves as a comprehensive reference for professional engineers, managers, and academics in manufacturing, industrial and mechanical engineering. **Advances in Electrical and Computer Technologies Springer**

Craig Kluever 's **Dynamic Systems: Modeling, Simulation, and Control** highlights essential topics such as analysis, design, and control of physical engineering systems, often composed of interacting mechanical, electrical and fluid subsystem components. The major topics covered in this text include mathematical modeling, system-response analysis, and an introduction to feedback control systems. **Dynamic Systems** integrates an early introduction to numerical simulation using MATLAB® 's Simulink for integrated systems. Simulink® and MATLAB® tutorials for both software programs will also be provided. The author 's text also has a strong emphasis on real-world case studies.

Developmental Robotics Springer

Power Electronics: Drive Technology and Motion Control explores the principles and practices of power electronics, emphasizing drive technology and motion control. The book covers the fundamentals of electric machine transformers, drive systems, electric traction and renewable energy in an e-Mobility chapter. Supported with illustrations and worked examples, the book covers theory, real life applications, and practical/industrial applications of power electronic drive technology and motion control. This book is intended for engineers, researchers and students who are interested in advanced control of power converters and control specialists who like to explore new applications of control theory.

Electronic power control is a coupling of electronic technology and applications from power engineering which rely on one another to provide cleaner electrical power, increased speed, reliability of power and accurate and efficient control of power. Includes illustrated diagrams to cover up-to-date industry applications Features in-depth worked examples to enhance understanding of power electronics theory and related practical applications Covers the fundamentals of electric machine transformers, drive systems, electric traction and renewable energy in an e-Mobility chapter

Theoretical method to increase the speed of continuous mapping in a three-dimensional laser scanning system using servomotors control Editorial UABC

This book categorizes the wide area of data-driven model-free controllers, reveals the exact benefits of such controllers, gives the in-depth theory and mathematical proofs behind them, and finally discusses their applications. Each chapter includes a section for presenting the theory and mathematical definitions of one of the above mentioned algorithms. The second section of each chapter is dedicated to the examples and applications of the corresponding control algorithms in practical engineering problems.

This book proposes to avoid complex mathematical equations, being generic as it includes several types of data-driven model-free controllers, such as Iterative Feedback Tuning controllers, Model-Free Controllers (intelligent PID controllers), Model-Free Adaptive Controllers, model-free sliding mode controllers, hybrid model - free and model - free adaptive - Virtual Reference Feedback Tuning controllers, hybrid model-free and model-free adaptive fuzzy controllers and cooperative model-free controllers. The book includes the topic of optimal model-free controllers, as well. The optimal tuning of model-free controllers is treated in the chapters that deal with Iterative Feedback Tuning and Virtual Reference Feedback Tuning. Moreover, the extension of some model-free control algorithms to the consensus and formation-tracking problem of multi-agent dynamic systems is provided. This book can be considered as a textbook for undergraduate and postgraduate students, as well as a professional reference for industrial and academic researchers, attracting the readers from both industry and academia.

Fuzzy Control Systems Springer Science & Business Media
This book introduces readers to the "Jaya" algorithm, an advanced optimization technique that can be applied to many physical and engineering systems. It describes the algorithm, discusses its differences with other advanced optimization techniques, and examines the applications of versions of the algorithm in mechanical, thermal, manufacturing, electrical, computer, civil and structural engineering. In real complex optimization problems, the number of parameters to be optimized can be very large and their influence on the goal function can be very complicated and nonlinear in character. Such problems cannot be solved using classical methods and advanced optimization methods need to be applied. The Jaya algorithm is an algorithm-specific parameter-less algorithm that builds on other advanced optimization techniques. The application of Jaya in several engineering disciplines is critically assessed and its success compared with other complex optimization techniques such as Genetic Algorithms (GA), Particle Swarm Optimization (PSO), Differential Evolution (DE), Artificial Bee Colony (ABC), and other recently developed algorithms.

From Babies to Robots Springer

Written for non-specialist users of electric motors and drives, this book explains how electric drives work and compares the performance of the main systems, with many examples of applications. The author's approach - using a minimum of mathematics - has made this book equally popular as an outline for professionals and an introductory student text. * First edition (1990) has sold over 6000 copies. Drives and Controls on the first edition: 'This book is very readable, up-to-date and should be extremely useful to both users and o.e.m. designers. I unhesitatingly recommend it to any busy engineer who needs to make informed judgements about selecting the right drive system.' New features of the second edition: * New section on the cycloconverter drive. * More on switched reluctance motor drives. * More on vector-controlled induction motor drives. * More on power switching devices. * New 'question and answer' sections on common problems and misconceptions. * Updating throughout. **Electric Motors and Drives is**

for non-specialist users of electric motors and drives. It fills the gap between specialist textbooks (which are pitched at a level which is too academic for the average user) and the more prosaic 'handbooks' which are filled with useful detail but provide little opportunity for the development of any real insight or understanding. The book explores most of the widely-used modern types of motor and drive, including conventional and brushless d.c., induction motors (mains and inverter-fed), stepping motors, synchronous motors (mains and converter-fed) and reluctance motors.

Modeling, Simulation, and Control Tata McGraw-Hill Education

A velocity feedback controller for the brushless DC motor was designed using the Hall effect sensors. In addition, the position control of the brushless DC motor was developed using an optical encoder to sense angular position changes and a microprocessor to provide the desired position control. A Pittman 5111 wdg 1 brushless DC motor was used for this study. The design of the digital tachometer and pulse width modulator for velocity control and the design of the Z-80 based microprocessor controller and software design are described in detail.

A Proceedings Volume from the 3rd IFAC Symposium, Sydney, Australia, 6-8 September 2004 CRC Press

The research and exploitation of optoelectronic properties in the industrial branch of electronics is becoming more popular each day due to the important role they play in the development of a large variety of sensors, devices, and systems for identifying, measuring, and constructing. While optoelectronics study the applications of electronic devices that source, detect, and transform light, machine vision generates and detects light in order to provide imaging-based automatic inspections and analysis for such applications as automatic object and environmental inspection, process control, and robot/mobile machine guidance in industry. Machine vision is less efficient without optoelectronics, and thus, it is important to investigate the theoretical approaches to different optoelectronic devices available for machine vision as well as current scanning technologies. Examining Optoelectronics in Machine Vision and Applications in Industry 4.0 focuses on the examination of emerging technologies for the design, fabrication, and implementation of optoelectronic sensors, devices, and systems in a machine vision approach to support industrial, commercial, and scientific applications. The book covers topics such as the design, fabrication, and implementation of sensors and devices as well as the development viewpoint of optoelectronic systems and artificial vision techniques using optoelectronic devices. The interaction and informational communication between all these mentioned devices in the complex solution of the same task is the subject of modern challenges in Industry 4.0. Thus, this book supports engineers, technology developers, academicians, researchers, and students who seek

machine vision techniques for detection, measurement, and 3D reconstruction.

Mechatronic Systems 2004 Springer Science & Business Media

Los escáneres Láser son dispositivos de escaneo óptico que miden la topografía de la superficie utilizando escaneo Láser fónico por punto de luz que se mueve a través de una superficie. Un nuevo sistema de visión técnica fue desarrollado en el Instituto de Ingeniería de la UABC, que consiste principalmente en un dispositivo de escaneo Láser usando triangulación dinámica para obtener coordenadas 3D de cualquier objeto examinado. En este sentido, el presente libro describe la sustitución de actuadores discretos por motores DC, para eliminar zonas muertas y realizar un escaneo Láser continuo en el campo del sistema de visión técnica.

Proceedings of KKA 2020—The 20th Polish Control Conference, Łódź, Poland, 2020 CRC Press

A comprehensive overview of an interdisciplinary approach to robotics that takes direct inspiration from the developmental and learning phenomena observed in children's cognitive development. Developmental robotics is a collaborative and interdisciplinary approach to robotics that is directly inspired by the developmental principles and mechanisms observed in children's cognitive development. It builds on the idea that the robot, using a set of intrinsic developmental principles regulating the real-time interaction of its body, brain, and environment, can autonomously acquire an increasingly complex set of sensorimotor and mental capabilities. This volume, drawing on insights from psychology, computer science, linguistics, neuroscience, and robotics, offers the first comprehensive overview of a rapidly growing field. After providing some essential background information on robotics and developmental psychology, the book looks in detail at how developmental robotics models and experiments have attempted to realize a range of behavioral and cognitive capabilities. The examples in these chapters were chosen because of their direct correspondence with specific issues in child psychology research; each chapter begins with a concise and accessible overview of relevant empirical and theoretical findings in developmental psychology. The chapters cover intrinsic motivation and curiosity; motor development, examining both manipulation and locomotion; perceptual development, including face recognition and perception of space; social learning, emphasizing such phenomena as joint attention and cooperation; language, from phonetic babbling to syntactic processing; and abstract knowledge, including models of number learning and reasoning strategies. Boxed text offers technical and methodological details for both psychology and robotics experiments.