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Such a discrete-time control system consists of four major parts: 1 The Plant which is a continuous-time dynamic system. 2 The Analog-to-Digital Converter (ADC). 3 The Controller (μP), a microprocessor with a " real-time " OS. 4 The Digital-to-Analog Converter (DAC) .

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Figure 1: A discrete time control input with zero order hold applied to a continuous time system. $G_k(j) = (1 - z^{-1})^{-1} G(s)$ For stability, the eigenvalues of G_m must have magnitude < 1 . So if the continuous time plant is stable ($\text{eig}(A) < 0$) the discrete time plant will have eigenvalues with magnitude less than 1.

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Discrete-Time Systems. 4. Design of Discrete-Time Control Systems by Conventional Methods. 5. State Space Analysis. 6. Pole Placement and Observer ...

Discrete Time Control Systems Ogata

Ogata wrote this textbook for senior undergraduate or first-year graduate students in engineering who have taken an introductory course in control systems as well as one in differential equations; familiarity with MATLAB is recommended.

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