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Figure 1: A discrete time control input with zero order hold applied to a

continuous time system. Gk j 1Hu(j): (11) For stability, the eigenvalues of Gmust have magnitude <1. So if the continuous time plant is stable (< eig (A) <0) the discrete time plant will have eigenvalues with magnitude less than 1.

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Such a discrete-time control system consists of four major parts: 1 The Plant which is a continuous-time dynamic system. 2 The Analog-to-Digital Converter (ADC). 3 The Controller (μP), a microprocessor with a "real-time" OS. 4 The Digital-to-Analog Converter (DAC) .

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