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FEEDBACK EXAMPLES 5. namics in the system (parameter errors, unmodeled effects, etc). The algorithm that computes the control action as a function of the sensor values is often called a control law. The system can be influenced externally by an operator who intr o- duces command signals to the system.

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Feedback Control of Dynamic Systems provides enough information, early and simply, so that a student can implement a controller in a digital computer, and an instructor can cover it in one lecture. This text is devoted to supporting students equally in their need to grasp both traditional and more modern topics of digital control.