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Causal signals are signals that are zero for all negative time, while anticausal are signals that are zero for all positive time. Noncausal signals are signals that have nonzero aluesv in both positive and negative time

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Definition 2 System is defined as any process in which input signals are transformed to output signals. Ex: Electrical circuit with an input signal  $v_i(t)$  and an output signal  $v_o(t)$  We will discuss systems in Section 1.2 in more detail. 1.1.1 Transformations of the independent variable of signals

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SIGNAL TRANSMISSION THROUGH LINEAR SYSTEMS Linear system, impulse response, Response of a linear system, Linear time-invariant (LTI) system, Linear time variant (LTV) system, the Transfer function of an LTI system. Filter characteristics of linear systems.

### **Fundamentals Of Signals Systems Solutions**

Addresses signal analysis using the DFT to extract the dominant cyclic components of a signal. Addresses the issue of noise, which often arises in engineering, business, finance, and other fields. For those interested in learning more about signals and systems.

[Signals and Systems: Theory and Applications](#) Fundamentals of signals and systems / Benoit Boulet.— 1st ed. p. cm. Includes index. ISBN 1-58450-381-5 (hardcover with cd-rom : alk.

paper) 1. Signal processing. 2. Signal generators. 3. Electric filters. 4. Signal detection. 5. System analysis. I. Title. TK5102.9.B68 2005 621.382'2—dc22 2005010054 07 7 6 5 4 3 [Kamen & Heck, Fundamentals of Signals and Systems Using ...](#)

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Administrivia Textbook: Fundamentals of Signals and Systems Using the Web and MATLAB by Edward W. Kamen and Bonnie S. Heck (Prentice-Hall, 3rd edition, 2007).. Teaching assistant: Hafeez Dhalla (al.dhalla [at] duke.edu) Coursework: Grades will be based on homeworks (30%), three in-class exams (45%), and a final exam (25%).

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Solution: A system is linear if it has both the scaling property and the additivity property. The scaling property is: If  $x(t)$  SYSTEM  $y(t)$ ; then  $cx(t)$  SYSTEM  $cy(t)$  for any constant  $c$ . The additivity property is: If  $x_1(t)$  SYSTEM  $y_1(t)$  and  $x_2(t)$  SYSTEM  $y_2(t)$ ; then  $[x_1(t)+x_2(t)]$  SYSTEM  $y_1(t)+y_2(t)$ .

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