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4 Goldstein 8.26 4.1 Part (a) In the given con guration, both springs elongate or

compress by the same magnitude. Suppose q denotes the position of the mass

m from the left end. At $t = 0$, $q(0) = a = 2$, but the unstretched lengths of both

springs are given to be zero. Therefore, the elongation (compression) of spring k_1

is q and the compression (elongation) of spring k_2 is q . The potential energy ...

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Derivations 1. Show that for a single particle with constant mass the

equation of motion implies the following differential equation for the

kinetic energy: $dT/dt = F \cdot v$ while if the mass varies with time the

corresponding equation is $d(mT)/dt = F \cdot p$. Answer: $dT/dt = d(1/2$

$mv^2)/dt = mv \cdot \dot{v} = ma \cdot v = F \cdot v$ with time variable mass, $d \dots$

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[Homer Reids Solutions to Goldstein Problems: Chapter 8. Problem 8.6 A Hamiltonian of one degree of freedom has the form \$H = \frac{1}{2}ap^2 + \frac{1}{2}bp^2 + q^2 + \frac{1}{2}kq^2\$, where \$a\$, \$b\$, \$k\$, and \$q\$ are constants. Note: I think there must be a misprint in the book; the coefficient of \$p^2\$ in the first term is printed there as \$1/2\$, which doesn't make sense dimensionally in light of the rest of the terms in ...](#) [Homework 9 | Hamiltonian Mechanics | Differential Geometry](#)

The constraint that the mass is on the wedge is $r = R + l(\cos \theta, \sin \theta)$, or $x = X + l \cos \theta$ and $y = l \sin \theta$ where l is the distance the mass traveled down the wedge. This is one constraint, which we can express as a function of x, y, X as $f = (x - X) \sin \theta - y \cos \theta = 0$.

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