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## RFID IEEE PAPER 2018

Member, IEEE, Young-Ha Shin<sup>3</sup>, Student Member, IEEE, and Hae-Won Park , Member, IEEE. Abstract—This paper presents a novel Representation-Free. Model Predictive Control (RF-MPC) framework for controlling. various dynamic motions of a quadrupedal robot in three. dimensional (3D) space.

## railway gate control IEEE PAPERS

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In this paper, our aim is to implement automatic railway gate control system at unmanned railway level crossings to prevent accidents that occur because of railroad intrusion and unawareness of the approaching train. The system also checks for any obstacle that gets . Automatic Railway Gate Control System Based on RFID, pressure sensor and servo motor

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Iterative Learning Control for RF Power Amplifier Linearization.

Abstract: This paper proposes a new technique to identify the parameters of a digital predistorter based on iterative learning control (ILC). ILC is a well-established control theory technique that can obtain the inverse of a system. Instead of focusing on identifying the predistorter parameters, the technique proposed here first uses an iterative learning algorithm to identify the optimal power amplifier (PA) input signal that ...

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ABSTRACT -This paper presents a new dual-band slot antenna fed by a Coplanar Waveguide (CPW) line suitable for Radio Frequency Identification ( RFID ) applications especially designed for RFID readers and it operates at the two microwaves frequencies 2.45 GHz and Implementing RFID In Library Methodlogies, Advantages and Disadvantages

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Reconfigurable RF impedance tuner for match control in ...

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