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of practical limits on  
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pp.) Reviewed by  
algorithms; however,  
there are no clear robot  
control examples in  
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Department of  
Electrical Engineering  
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...  
In the case of an  
open chain robot  
such as the  
industrial  
manipulator of  
Figure 1.1(a), all  
of its joints are  
independently

actuated. This is  
the essential idea  
behind the degrees  
of freedom of a  
robot: it is the sum  
of all the  
independently  
actuated degrees of  
freedom of the  
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