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the robot. 55 Jog override (manual traversing velocity).  
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- Page 1 of 1 They must be integrated individually  
by means of menu entries in the file softkeyKUKA.  
The axes of the robot system lrcl here synchronized  
in such a way that the path velocity remains  
constant along this circular path.

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Forum - Page 1 of 1. In particular, other  
composites and arrays can also form part of a  
composite. If the frequency has not been set  
correctly, it can be altered using menu item “.

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stand--alone mode or with an external  
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equipment through the robot system, the  
connectors X20, X7, X21, X19, X1 and X01 are  
provided. These connectors Page 7/28 Page  
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Press the softkey " ExtBase Jrcl at the bottom left of the display in order to enter data for this kinematic system.

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2.1.1 Programs, data lists and modules The KRC saves the program code in files with the file extension SRC. Permanent data are saved in so-called data lists, files with the file extension DAT. A module consists of an SRC file and a DAT file with the same name.

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