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on the classical control theory and modern control theory. A brief introduction of robust control theory is included in Chapter 10. Automatic control is essential in any field of engineering and science. Automatic control is an important and integral part of space-vehicle systems, robotic systems, mod-

NEW - Chapter 10 first discusses PID control in general and then presents two-degrees-of-freedom control systems—Presents a computational (MATLAB) method to determine system parameters so the system will have desired transient characteristics. NEW - Improved chapter on the design of control systems in state space (Chapter 12)—Treats pole placement and observer design.

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