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N. Gurari and A. M. Okamura (2014) Compliance Perception using Natural and Artificial Motion Cues. In *Multisensory Softness - Perceived Compliance from Multiple Sources of Information*, pages 189-217. . Springer-Verlag.

Massimiliano Di Luca | PhD Cognitive Science - ResearchGate

Artificial Softness. Multisensory Softness

focuses on the cognitive mechanisms underlying the use of multiple sources of information in softness perception. Divided into three sections, the first Perceptual Softness deals with the sensory components and computational requirements of softness perception, the second Sensorimotor Softness looks at...

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Compliance perception (i.e., object softness) is a case of active sensing, because we need to interact with the object in order to collect sensory information. For this, there is no single sensor that captures compliance. Our

brain needs to combine several sensory signals to obtain an estimate.

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tually recover the compliance or material elasticity of an object. Thus, the notion of softness involves the extraction of object properties from stresses and strains, or forces and displacements, that are felt during exploration. Most prior research has investigated compliance perception via manual touch (Harper and Stevens 1964;

haptic and multisensory stiffness perception is due to the interaction between sensory information

derived from the skin, the muscles and the tendons, among others, all of which play an important role in properly perceiving material features of objects through the sense of touch.

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It is possible to distinguish between two main types of softness perception—one pertaining to the surface material qualities of a palpated object and the other linked to volumetric compliance.

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Multisensory Softness: Perceived Compliance From Multiple Sources Of Information by Di Luca, Massimiliano (Edt) Offers a unique multidisciplinary overview of how humans interact with soft objects and how multiple sensory signals are used to perceive material properties, with an emphasis on object

deformability.

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Perceptual Softness deals with the sensory
components and computational
requirements of softness perception, the
second Sensorimotor Softness looks at the
motor components of the interaction with
soft objects and the final part Artificial
Softness focuses on the identification of

exploitable guidelines to help replicate
softness in artificial environments.

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