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On this basis, H1 may be viewed as a time-invariant system with memory. System H2 is causal because the output does not appear before the input. The

duration of the output is longer than that of the input. This suggests that H2 must have memory. It is time-invariant. System H3 is noncausal because the output appears before the input.

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bytes/sample 2 channels 75 minutes 60 seconds/minute = 7:938 108 ...

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using MATLAB 0.5 ... $s = 1$ the discrete
signal has lost information. Solution As
we will see later, the sampling period of
 $x(t)$ with a frequency of $\max = 2\pi f$ $\max =$
 2π should satisfy

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