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Chapter 2 Exercise C - Solutions to Linear Algebra Done Right

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Chapter 3 Exercise A - Solutions to Linear Algebra Done Right

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To visualize the equations, I recommend Google Chrome with the extension TeX All the Things or GitHub with MathJax. Solution Of Linear Algebra Done Denote the set in question by A in each part. (a) Let $v, w \in A$, $v = (x_1, x_2, x_3)$, $w = (y_1, y_2, y_3)$. Then $x_1 + 2x_2 + 3x_3 = 0$ and $y_1 + 2y_2 + 3y_3 = 0$, so that $0 = x_1 + 2x_2 + 3x_3 + y_1 + 2y_2 + 3y_3 = (x_1 + y_1) + 2(x_2 + y_2) + 3(x_3 + y_3)$, so $v + w \in A$. Similarly $0 = a_0 = ax_1 + 2ax_2 + 3ay_3$, so $av \in A$.

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Solving this system of equations, we have $a = -1 - x - y$, $b = -1 + x - y$, $c = 1 - x + y$. It is clear that scalars a, b, c are not all zero because $b + c = 1$. Hence w_1, w_2, w_3 are linearly dependent as well. Suppose the system $v_1, v_2, \dots, v_r, v_{r+1}$ is linearly dependent, we argue it by contradiction.

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1. Solution: Let u_1, u_2, \dots, u_n be a basis of U . Thus $n = \dim U = \dim V$. Hence u_1, u_2, \dots, u_n is a linearly... 2. Solution: The dimension of a subspace U of R^2 can only be $0, 1, 2$. If $\dim U = 0$, then $U = \{0\}$. If $\dim U = 2, \dots$ 3. Solution: It is similar to Problem 2. If $\dim U = 2, \dots$

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Sheldon Axler Linear Algebra Done Right - Yikun Zhang
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Solution: We show that if $b = c = 0$, then T is linear. Let $f, g \in P(\mathbb{R})$, then we have $(f + g)(4) = f(4) + g(4)$ and $(f + g)'(4) = f'(4) + g'(4)$. It is easy to check. Moreover, by linearity of integration, one has $\int_{-1}^2 (f + g)(x) dx = \int_{-1}^2 f(x) dx + \int_{-1}^2 g(x) dx$. By the above, it follows that $T(f + g) = (3(f + g)(4) + 5(f + g)'(4)) \int_{-1}^2 (f + g)(x) dx = (3 \dots$

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Clearly $F_3 = U_1 + U_2 + U_3$ because an arbitrary vector $(x, y, z) \in F_3$ can be written as $(x, y, z) = (x, y, 0) + (0, 0, z) + (0, 0, 0)$, where the first vector on the right side is in U_1 , the second vector is in U_2 , and the third vector is in U_3 . However, F_3 does not equal the direct sum of U_1, U_2, U_3 because the vector $(0, 0, 0)$ can be written in two different ways as $u_1 + u_2 + u_3$, with each $u_j \in U_j$.
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