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# Stabilization And Control Of Fractional Order Systems A Sliding Mode Approach Lecture Notes In Electrical Engineering

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Fractional Dynamical Systems Springer

This book introduces applications of mathematics and fuzzy mathematics in decision science, fuzzy geometric programming and fuzzy optimization as well as operations research and management, based on 44 research papers presented at three successful conferences: (1) The International Conference on Mathematics and Decision Science (ICMDS), September 12 – 15, 2016, Guangzhou University, Guangzhou, China ([www.icodm2020.com](http://www.icodm2020.com)). (2) Academic Conference on 30th

Anniversary of Fuzzy Geometric Programming Advanced by Professor Cao Bingyuan and his 40 education years (ACFGPACE), July 30 to August 1, 2016, Guangzhou University, Guangzhou, China. (3) The third annual meeting of Guangdong Operational Research Society (TAMGORS), October 22 – 23, 2016, Foshan University, Guangdong, China. The book is a valuable resource for students, graduates, teachers and other professionals in the field of applied mathematics, artificial intelligence

and computers, fuzzy systems and decision-making, as well as operations research and management. Advances in Time-Delay Systems Springer Nature This book at hand is an appropriate addition to the field of fractional calculus applied to control systems. If an engineer or a researcher wishes to delve into fractional-order systems, then this book has many collections of such systems to work upon, and this book also tells the reader about how one can convert an integer-order system into an appropriate fractional-order one through an efficient and simple algorithm. If the reader further wants to explore the

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controller design for the fractional-order systems, then for them, this book provides a variety of controller design strategies. The use of fractional-order derivatives and integrals in control theory leads to better results than integer-order approaches and hence provides solid motivation for further development of control theory. Fractional-order models are more useful than the integer-order models when accuracy is of paramount importance. Real-time experimental validation of controller design strategies for the fractional-order plants is available. This book is beneficial to the academic institutes for postgraduate and

advanced research-level that need a specific textbook on fractional control and its applications in robotic manipulators. The book is also a valuable teaching and learning resource for undergraduate and postgraduate students. *Distributed-Order Dynamic Systems* CRC Press Systematically presents the input-output finite-time stability (IO-FTS) analysis of dynamical systems, covering issues of analysis, design and robustness. The interest in finite-time control has continuously grown in the last fifteen years. This book systematically presents the input-output finite-time stability (IO-FTS) analysis of dynamical systems, with specific

reference to linear time-varying systems and hybrid systems. It discusses analysis, design and robustness issues, and includes applications to real world engineering problems. While classical FTS has an important theoretical significance, IO-FTS is a more practical concept, which is more suitable for real engineering applications, the goal of the research on this topic in the coming years. Key features: Includes applications to real world engineering problems. Input-output finite-time stability (IO-FTS) is a practical concept, useful to study the behavior of a dynamical system within a finite interval of time. Computationally tractable conditions

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are provided that render the technique applicable to time-invariant as well as time varying and impulsive (i.e. switching) systems. The LMIs formulation allows mixing the IO-FTS approach with existing control techniques (e. g. H<sup>2</sup> control, optimal control, pole placement, etc.). This book is essential reading for university researchers as well as post-graduate engineers practicing in the field of robust process control in research centers and industries. Topics dealt with in the book could also be taught at the level of advanced control courses for graduate students in the department of electrical and computer engineering, mechanical

engineering, aeronautics and astronautics, and applied mathematics. **Advanced, Contemporary Control**  
**Springer Science & Business Media**  
A treatise on investigating tracking control and synchronization control of fractional-order nonlinear systems with system uncertainties, external disturbance, and input saturation  
**Robust Adaptive**

**Control for Fractional-Order Systems, with Disturbance and Saturation** provides the reader with a good understanding on how to achieve tracking control and synchronization control of fractional-order nonlinear systems with system uncertainties, external disturbance, and input saturation. Although some texts have touched upon control of

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fractional-order systems, the issues of input saturation and disturbances have rarely been considered together. This book offers chapter coverage of fractional calculus and fractional-order systems; fractional-order PID controller and fractional-order disturbance observer; design of fractional-order controllers for nonlinear chaotic systems and some applications; sliding mode control for fractional-order nonlinear systems based on disturbance observer; disturbance observer based neural control for an uncertain fractional-order rotational mechanical system; adaptive neural tracking control for uncertain fractional-order chaotic systems subject to input saturation and disturbance; stabilization control of continuous-time fractional positive systems based on disturbance observer; sliding mode synchronization control for fractional-order chaotic systems with disturbance; and more. Based on the approximation ability of the neural network (NN), the adaptive neural control schemes are reported for uncertain fractional-order nonlinear systems. Covers the

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disturbance estimation techniques that have been developed to alleviate the restriction faced by traditional feedforward control and reject the effect of external disturbances for uncertain fractional-order nonlinear systems. By combining the NN with the disturbance observer, the disturbance observer based adaptive neural control schemes have

been studied for uncertain fractional-order nonlinear systems with unknown disturbances. Consider, together, the issue of input saturation and the disturbance for the control of fractional-order nonlinear systems in the present of system uncertainty, external disturbance, and input saturation. Robust Adaptive Control for Fractional-Order Systems, with

Disturbance and Saturation can be used as a reference for the academic research on fractional-order nonlinear systems or used in Ph.D. study of control theory and engineering. *Advances in Non-Integer Order Calculus and Its Applications* Springer Nature. This book collects papers from the 8th Conference on Non-Integer Order Calculus and

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Its Applications that have been held on September 20-21, 2016 in Zakopane, Poland. The preceding two conferences were held in Szczecin, Poland in 2015, and in Opole, Poland, in 2014. This conference provides a platform for academic exchange on the theory and application of fractional calculus between domestic and international

universities, research institutes, corporate experts and scholars. The Proceedings of the 8th Conference on Non-Integer Order Calculus and Its Applications 2016 brings together rigorously reviewed contributions from leading international experts. The included papers cover novel various important aspects of mathematical foundations of fractional

calculus, modeling and control of fractional systems as well as controllability, detectability, observability and stability problems for this systems. **Trends in Advanced Intelligent Control, Optimization and Automation** John Wiley & Sons This volume presents various aspects of non-integer order systems, also known as fractional systems, which have recently

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attracted an increasing attention in the scientific community of systems science, applied mathematics, control theory. Non-integer systems have become relevant for many fields of science and technology exemplified by the modeling of signal transmission, electric noise, dielectric polarization, heat transfer, electrochemical reactions, thermal processes, acoustics, etc. The content is divided into six parts, every of which

considers one of the currently relevant problems. In the first part the Realization problem is discussed, a special focus on positive systems. The second part considers stability of certain classes of non-integer order systems with and without delays. The third part is focused on such important aspects as controllability, observability and optimization especially in discrete time. The fourth part is focused on distributed

systems where non-integer calculus leads to new and interesting results. The next part considers problems of solutions and approximations of non-integer order equations and systems. The final and most extensive part is devoted to applications. Problems from mechatronics, biomedical engineering, robotics and others are all analyzed and solved with tools from fractional systems. This volume came to fruition thanks to high level



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of talks and interesting discussions at RRNR 2013 - 5th Conference on Non-integer Order Calculus and its Applications that took place at AGH University of Science and Technology in Kraków, Poland, which was organized by the Faculty of Electrical Engineering, Automatics, Computer Science and Biomedical Engineering.

**Application of Intelligent Control Algorithms to Study the**

**Dynamics of Hybrid Power System**  
Springer  
A treatise on investigating tracking control and synchronization control of fractional-order nonlinear systems with system uncertainties, external disturbance, and input saturation  
Robust Adaptive Control for Fractional-Order Systems, with

Disturbance and Saturation provides the reader with a good understanding on how to achieve tracking control and synchronization control of fractional-order nonlinear systems with system uncertainties, external disturbance, and input saturation. Although some texts have touched upon control of fractiona

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1-order systems, the issues of input saturation and disturbances have rarely been considered together. This book offers chapter coverage of fractional calculus and fractional-order systems; fractional-order PID controller and fractional-order disturbance observer; design of fractional-order controllers for nonlinear chaotic systems and some applications; sliding mode control for fractional-order nonlinear systems based on disturbance observer; disturbance observer based neural control for an uncertain fractional-order rotational mechanical system; adaptive neural tracking control for uncertain fractional-order chaotic systems subject to input saturation and disturbance; stabilization control of continuous-time fractional positive systems based on disturbance observer; sliding mode synchronization control for fractional

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and input saturation Robust Adaptive Control for Fractional-Order Systems, with Disturbance and Saturation can be used as a reference for the academic research on fractional-order nonlinear systems or used in Ph.D. study of control theory and engineering. Advanced Syn

chronization Control and Bifurcation of Chaotic Fractional-Order Systems Springer This book aims to provide the basic theory of fractional calculus and its applications based on practical schemes and approaches, illustrated with applicable engineering and technical examples,

especially focusing on the fractional-order controller design. In the development of this book, the essential theorems and facts in the first two chapters are proven with rigorous mathematical analyses. In addition, the commonly used definitions of Grünwald-Letnikov, Riemann-Liouville, Caputo, and

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Miller-Ross fractional derivatives are introduced with their properties proved and linked to fractional-order controller design. The last chapter presents several enlightening scenarios of fractional-order control designs, for example, the suppression of machining chatter, the nonlinear motion

control of a multilink robot, the simultaneous tracking and stabilization control of a rotary inverted pendulum, and the idle speed control of an internal combustion engine (ICE).  
**Recent Advances in Control Problems of Dynamical Systems and Networks** John Wiley & Sons  
Mathematical Techniques of Fractional Order Systems

illustrates advances in linear and nonlinear fractional-order systems relating to many interdisciplinary applications, including biomedical, control, circuits, electromagnetics and security. The book covers the mathematical background and literature survey of fractional-order calculus and generalized fractional-order circuit theorems from different

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<p>perspectives in design, analysis and realizations, nonlinear fractional-order circuits and systems, the fractional-order memristive circuits and systems in design, analysis, emulators, simulation and experimental results. It is primarily meant for researchers from academia and industry, and for those working in areas such as control engineering,</p>	<p>electrical engineering, computer science and information technology. This book is ideal for researchers working in the area of both continuous-time and discrete-time dynamics and chaotic systems. Discusses multidisciplinary applications with new fundamentals, modeling, analysis, design, realization and experimental results</p>	<p>Includes circuits and systems based on new nonlinear elements. Covers most of the linear and nonlinear fractional-order theorems that will solve many scientific issues for researchers. Closes the gap between theoretical approaches and real-world applications. Provides MATLAB® and Simulink code for many applications in the book</p>
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Mathematical  
Methods in  
Engineering

Springer

This book aims to systematically review and design different intelligent control algorithms for the small-signal stability assessment of HPS. With the growing consciousness of global warming and the fast depletion of natural power generation resources, the existing power system is on the

verge of transitions to a "hybrid power system (HPS)" integrated with distributed energy resources. The recent results and requirements for the developments of intelligent control algorithms have motivated the authors to introduce this book for extensively analyzing the performance of HPS against unknown/uncertain

disturbances. This book introduces fractional-order resilient control methodologies for arresting small-signal instability of HPS. The prospective investigation has been performed on the MATLAB platform. This book is helpful for undergraduate, postgraduate students, and research scholars working in power system stability, control

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applications, and soft computing in particular. *Low-Complexity Controllers for Time-Delay Systems* Springer Science & Business Media Engineering technology development and implementation play an important role in making the industry more sustainable in an increasingly competitive world. This book covers significant recent

developments in both fundamental and applied research in the engineering field. Domains of application include, but are not limited to, Intelligent Control Systems and Optimization, Signal Processing, Sensors, Systems Modeling and Control, Robotics and Automation, Industrial and Electric Engineering, Production and

Management. This book is an excellent reference work to get up to date with the latest research and developments in the fields of Automation, Mechatronics and Industrial Engineering. It aims to provide a platform for researchers and professionals in all relevant fields to gain new ideas and establish great



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achievements  
in scientific  
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Theoretical  
Developments  
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Applications  
of Non-Integer  
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Springer  
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Dynamics and Control provides a comprehensive overview of recent advances in the areas of nonlinear dynamics, vibration and control with analytical, numerical, and experimental results. This book provides an overview of recent discoveries in fractional control, delves into fractional variational principles and differential equations, and applies advanced techniques in fractional calculus to solving complicated mathematical and physical problems. Finally, this book also discusses the role that fractional order modeling can play in complex systems for engineering and science. *Proceedings of the International Conference on Advanced Intelligent Systems and Informatics 2019* Springer This edited book introduces readers to new analytical techniques and controller design schemes used to solve the emerging "hottest" problems in dynamic control systems and networks. In recent years, the study of dynamic systems and networks has faced major changes and challenges with the rapid advancement of IT technology, accompanied by the 4th Industrial Revolution. Many new factors that now have to be

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considered, and which haven't been addressed from control engineering perspectives to date, are naturally emerging as the systems become more complex and networked. The general scope of this book includes the modeling of the system itself and uncertainty elements, examining stability under various criteria, and controller design techniques to achieve specific control objectives in various dynamic systems and networks. In terms of traditional stability matters, this includes the following special issues: finite-time stability and stabilization, consensus/synchronization, fault-tolerant control, event-triggered control, and sampled-data control for classical linear/nonlinear systems, interconnected systems, fractional-order systems, switched systems, neural networks, and complex networks. In terms of introducing graduate students and professional researchers studying control engineering and applied mathematics to the latest research trends in the areas mentioned above, this book offers an excellent guide.

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Nonlinear Dynamics and Applications Springer Nature  
 This book presents a wide and comprehensive spectrum of issues and problems related to fractional-order dynamical systems. It is meant to be a full-fledged, comprehensive presentation of many aspects related to the broadly perceived fractional-order dynamical systems which constitute an order extension of the traditional integer-order descriptions. This implies far-reaching consequences, both analytic and algorithmic, because in general properties of the traditional integer-order systems cannot be directly extended by a straightforward generalization to fractional-order systems, modeled by fractional-order differential equations involving derivatives of a non-integer order. This can be useful for describing and analyzing, for instance, anomalies in the behavior of various systems, chaotic behavior, etc. The book contains both analytic contributions with state-of-the-art and theoretical foundations, algorithmic implementation

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so that the reader can learn about, and get ready to, design these applications. The book also includes the different techniques employed to c omprehensivel y and straigh tforwardly design fracti onal-order sy stems/devices . Furthermore, a lot of mathematics is available in the literature for solving the fractiona l-order calculus for system

application. However, a small portion is employed in the design of fractional-order systems. This book introduces the mathematics that has been employed explicitly for fractiona l-order systems. Students and scholars who wants to quickly understand the field of fractional-order systems and contribute to its different domains and

applications will find this book a welcomed resource. Presents a simple and comprehensive understanding of the field of fractional-order systems Offers practical knowledge on the design of fractional-order systems for different applications Exposes users to the possible new areas of applications of fractional-order systems Robust Adaptive Control for Fr

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Disturbance and control Springer  
Saturation John technology, Science &  
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This book applications, "Fractional-  
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from both theoretical and applied perspectives. The desire to develop more effective and efficient tools and techniques for dealing with complex processes and systems has been a natural inspiration for the emergence of numerous fields of science and technology, in particular control and automation and, more recently, robotics. The contributions gathered here concern the development of methods and algorithms to determine best practices regarding broadly perceived decisions or controls. From an engineering standpoint, many of them focus on how to automate a specific process or complex system. From a tools-based perspective, several contributions address the development of analytic and algorithmic methods and techniques, devices and systems that make it possible to develop and subsequently implement the automation and robotization of crucial areas of human activity. All topics discussed are illustrated with sample applications.